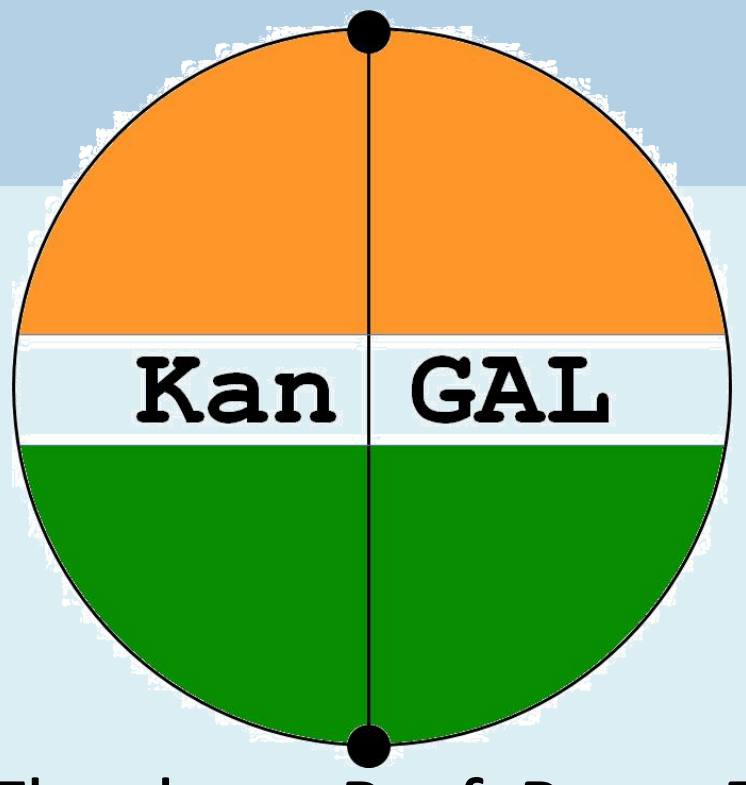


A Dimensionally-Aware Genetic Programming Architecture for Automated Innovization



Automated Innovization

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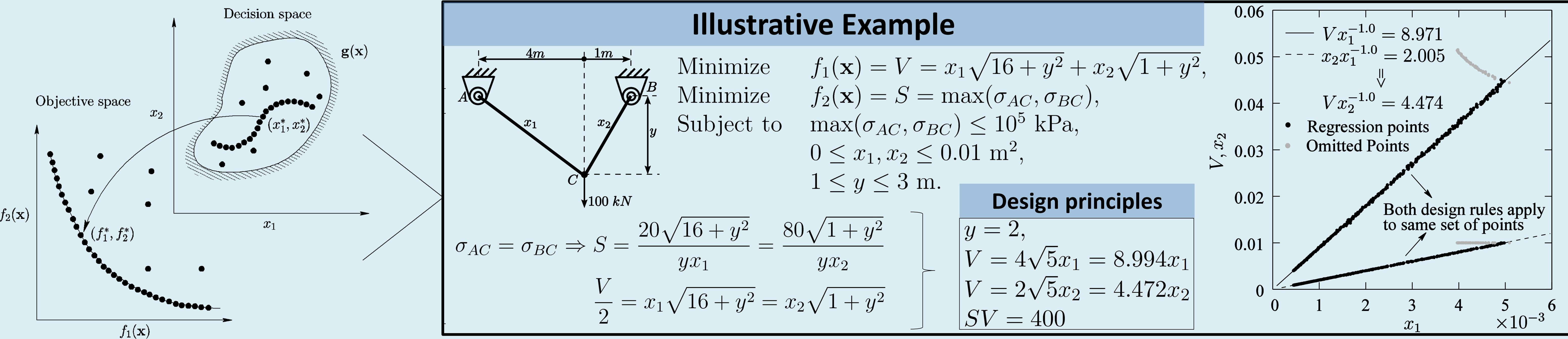
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Thanks to Prof. Peter Fleming for Presenting this work

<http://www.iitk.ac.in/kangal/pub.shtml>

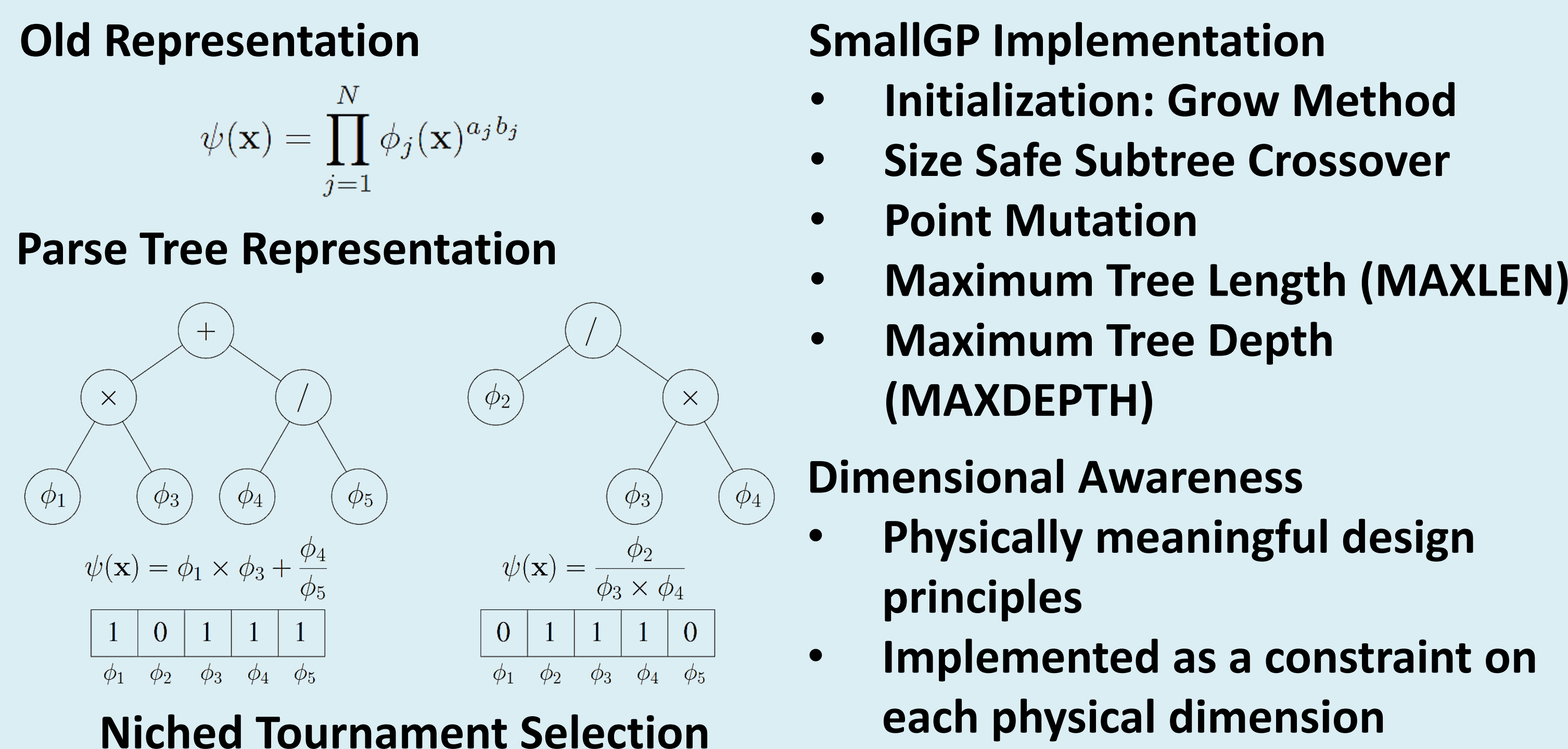
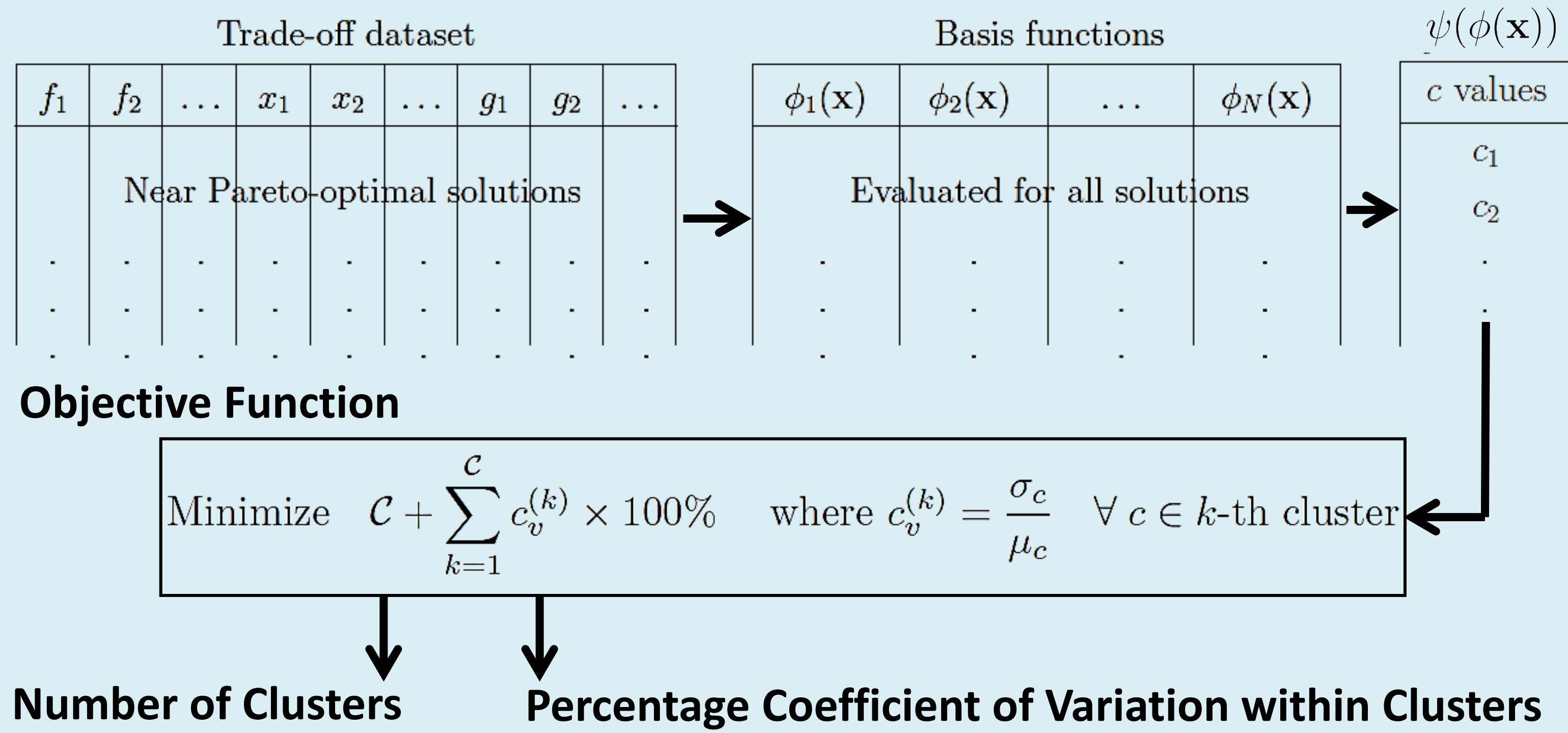
Innovization: Innovation through Multi-objective Optimization



Automated Innovization using Dimensionally-Aware Genetic Programming (GP)

Methodology: Grid-based Clustering and Optimization

Extension: Generalization of $\psi(\phi(\mathbf{x}))$ using Parse Tree Representation



Results on Engineering Design Problems

Design Principles for Truss Problem (Above)

Design Principles for Welded-Beam Problem

Design Principles for Metal-Cutting Problem

Notation	Design Principle (DP) $\psi(\mathbf{x}) = \text{constant}$	Significance	Basic Dimensions		
			Mass	Length	Time
DP1	$y = \text{constant}$	86.60%	0.0	1.0	0.0
DP2	$S \times V = \text{constant}$	87.00%	1.0	2.0	-2.0
DP3	$S \times x_1 = \text{constant}$	85.00%	1.0	1.0	-2.0
DP4	$S \times V \times y = \text{constant}$	87.00%	1.0	3.0	-2.0
DP5	$(V \times y)/x_2 = \text{constant}$	86.20%	0.0	2.0	0.0
DP6	$(V \times y)/x_1 = \text{constant}$	88.20%	0.0	2.0	0.0
DP7	$V/x_1 = \text{constant}$	86.40%	0.0	1.0	0.0
DP8	$V/(S \times x_1 \times x_2) = \text{constant}$	87.20%	-1.0	0.0	2.0
DP9	$V^2/(x_1 \times x_2) = \text{constant}$	87.40%	0.0	2.0	0.0
DP10	$y/(S \times x_1) = \text{constant}$	88.00%	-1.0	0.0	2.0
DP11	$x_2/x_1 = \text{constant}$	83.80%	0.0	0.0	0.0
DP12	$(S \times V \times x_2 \times y)/x_1 = \text{constant}$	88.00%	1.0	3.0	-2.0
DP13	$V/x_2 = \text{constant}$	86.80%	0.0	1.0	0.0
DP14	$(S \times V^2 \times y)/x_1 = \text{constant}$	87.20%	1.0	4.0	-2.0
DP15	$(x_2 \times y)/x_1 = \text{constant}$	86.40%	0.0	1.0	0.0
DP16	$x_2/(S \times x_1^2) = \text{constant}$	86.40%	-1.0	-1.0	2.0
DP17	$V^2/(x_1 \times x_2 \times y) = \text{constant}$	91.40%	0.0	1.0	0.0
DP18	$(S \times V^2)/x_2 = \text{constant}$	87.20%	1.0	3.0	-2.0
DP19	$S \times x_2 \times y = \text{constant}$	87.00%	1.0	2.0	-2.0
DP20	$(x_2 \times y)/(S \times x_1^2) = \text{constant}$	86.80%	-1.0	0.0	2.0

Minimize $f_1(\mathbf{x}) = C = 1.10471h^2l + 0.04811tb(14.0 + l)$,
 Minimize $f_2(\mathbf{x}) = D = \frac{2.1952}{t^3b}$,
 Subject to $\begin{cases} \tau(\mathbf{x}) \leq 13,600$ psi; $\sigma(\mathbf{x}) \leq 30,000$ psi; $b \geq h$; $P_c(\mathbf{x}) \geq 6,000$ lb
 $0.125 \leq h, b \leq 5.0$ in.; $0.1 \leq l, t \leq 10.0$ in.

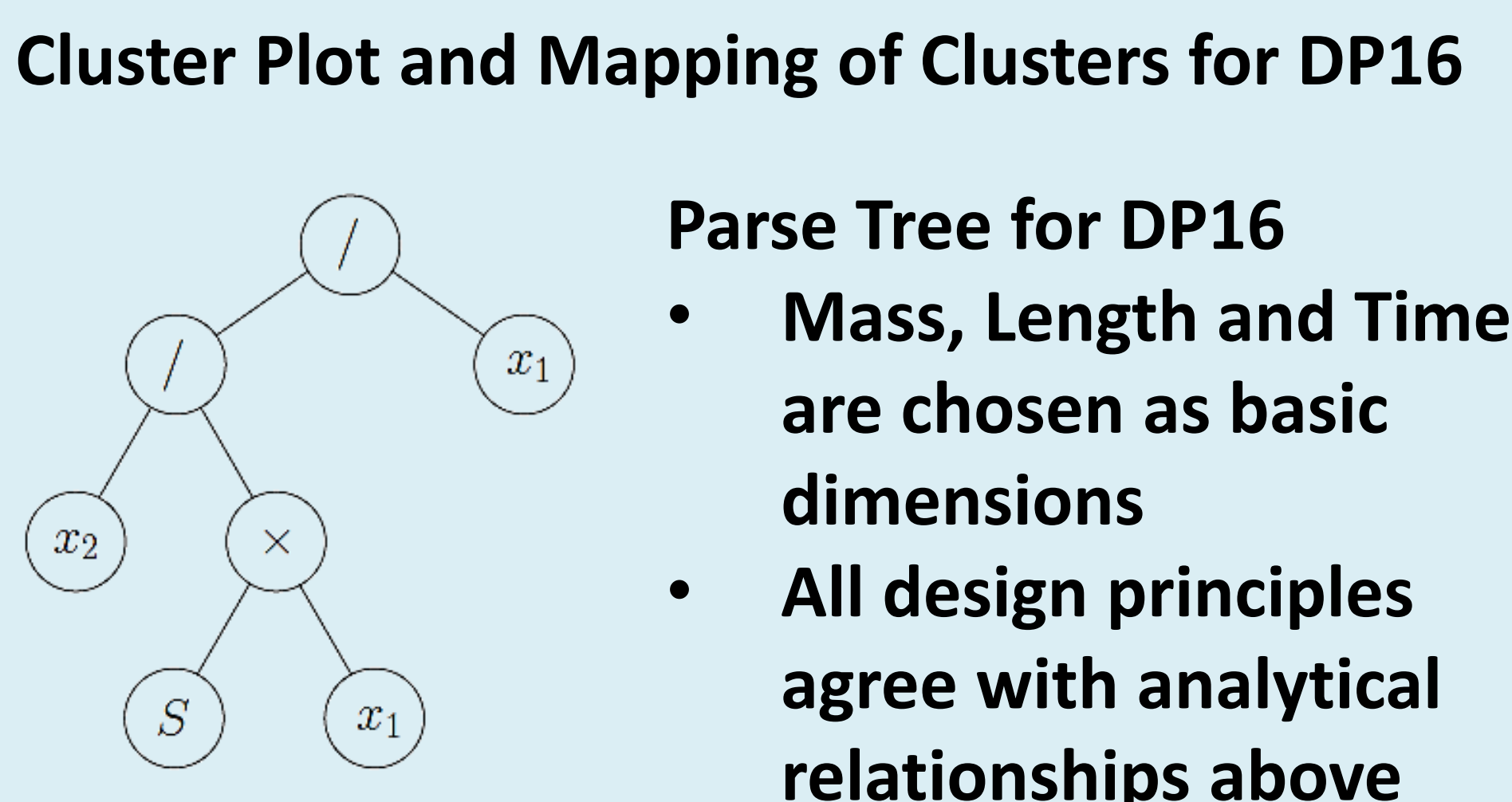
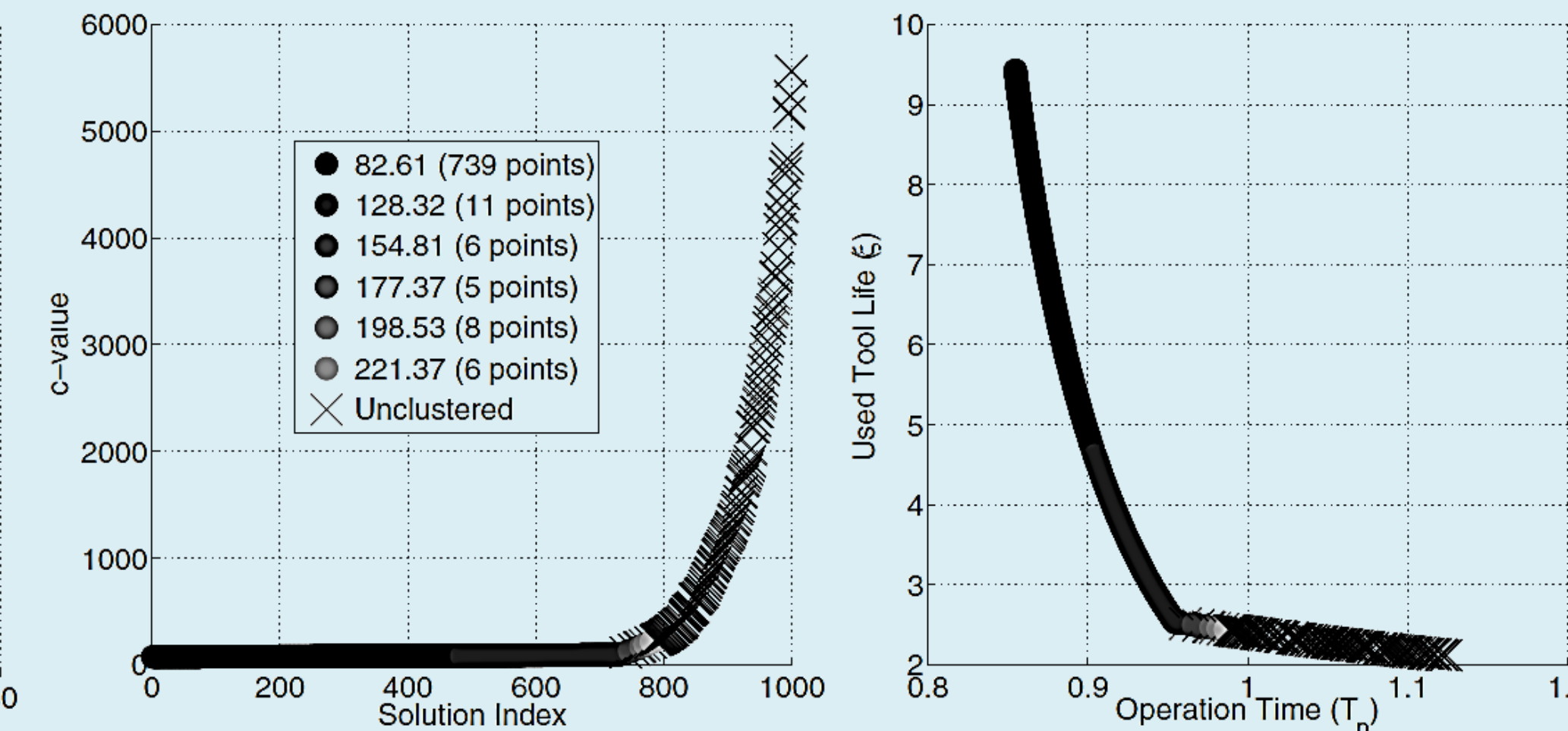
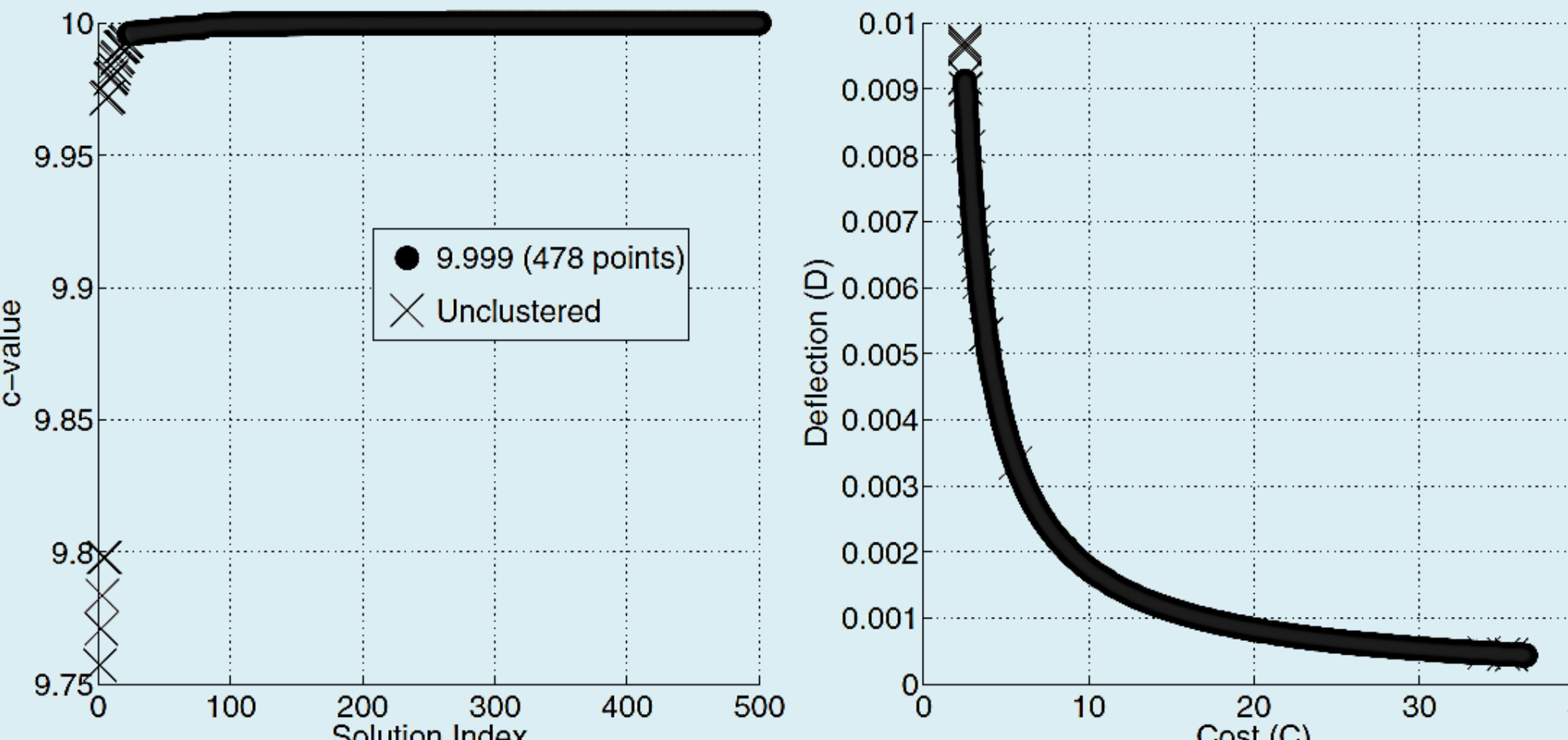
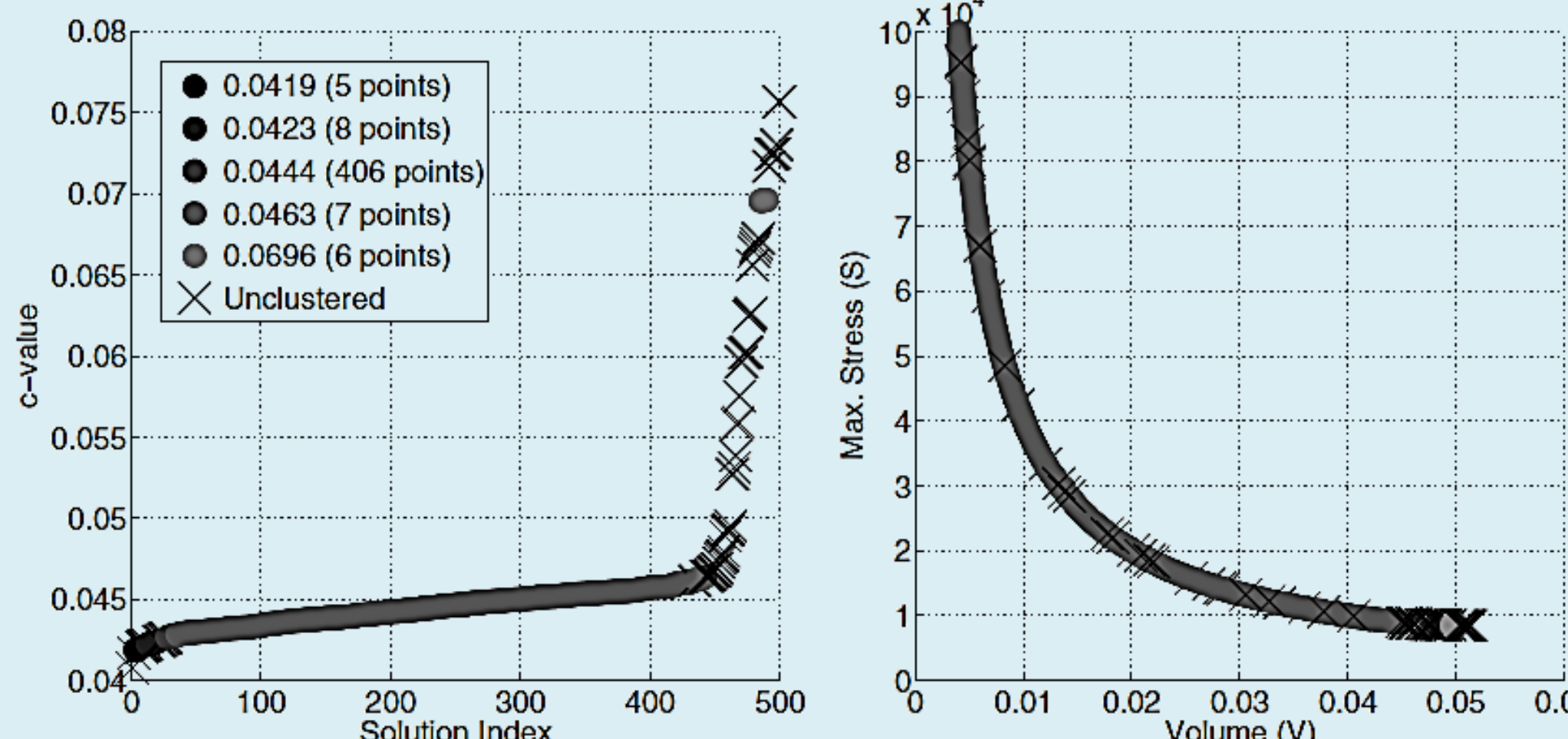
where $\tau(\mathbf{x}) = \sqrt{(\tau')^2 + (\tau'')^2 + (l\tau''')/\sqrt{0.25(l^2 + (h+t)^2)}}$,
 $\tau' = \frac{6,000}{\sqrt{2}hl}$, $\tau'' = \frac{6,000(14+0.5l)\sqrt{0.25(l^2 + (h+t)^2)}}{2[0.707hl(l^2 + 0.25(h+t)^2)]}$,
 $\sigma(\mathbf{x}) = \frac{504,000}{t^2b}$,
 $P_c(\mathbf{x}) = 64,746.022(1 - 0.0282346t)tb^3$.

Notation	Design Principle (DP) $\psi(\mathbf{x}) = \text{constant}$	Significance	Basic Dimensions			
			Mass	Length	Time	Cost
DP1	$(D + t) = \text{constant}$	95.20%	0.0	1.0	0.0	0.0
DP2	$t = \text{constant}$	95.60%	0.0	1.0	0.0	0.0
DP3	$D \times b = \text{constant}$	95.00%	0.0	2.0	0.0	0.0
DP4	$D \times b \times t = \text{constant}$	95.60%	0.0	3.0	0.0	0.0
DP5	$\sigma \times b = \text{constant}$	94.80%	1.0	0.0	-2.0	0.0
DP6	$\sigma \times b \times t = \text{constant}$	95.60%	1.0	1.0	-2.0	0.0
DP7	$D/\sigma = \text{constant}$	95.60%	-1.0	2.0	2.0	0.0
DP8	$D/(\sigma \times t) = \text{constant}$	95.60%	-1.0	1.0	2.0	0.0

Minimize $f_1(\mathbf{x}) = T_p(\mathbf{x}) = 0.15 + 219912 \left(\frac{1 + \frac{0.25}{MRR(\mathbf{x})}}{MRR(\mathbf{x})} \right) + 0.05$ min
 Minimize $f_2(\mathbf{x}) = \xi(\mathbf{x}) = \frac{219912}{MRR(\mathbf{x})T(\mathbf{x})} \times 100\%$
 Subject to $\begin{cases} P(\mathbf{x}) \leq \eta P^{max}$; $F_c(\mathbf{x}) \leq F_c^{max}$; $R(\mathbf{x}) \leq R^{max}$
 $250 \leq v \leq 400$ m/min; $0.15 \leq f \leq 0.55$ mm/rev; $0.5 \leq a \leq 6$ mm

where $T(\mathbf{x}) = \frac{5.48 \times 10^9}{v^{3.746} f^{0.696} a^{0.460}}$, $MRR(\mathbf{x}) = 1000 v f a$
 $P(\mathbf{x}) = \frac{v F_c(\mathbf{x})}{60000}$, $F_c(\mathbf{x}) = \frac{6.56 \times 10^3 f^{0.917} a^{1.10}}{v^{0.286}}$, $R(\mathbf{x}) = \frac{125 f^2}{r_n}$

Notation	Design Principle (DP) $\psi(\mathbf{x}) = \text{constant}$	Significance	Basic Dimensions			
			Mass	Length	Time	Life
DP1	$v/(f^2 \times \xi) = \text{constant}$	72.70%	0.0	-1.0	-1.0	-1.0
DP2	$(a \times v)/f = \text{constant}$	74.60%	0.0	1.0	-1.0	0.0
DP3	$v/(f^2 \times T_p \times \xi) = \text{constant}$	73.40%	0.0	-1.0	-2.0	-1.0
DP4	$f = \text{constant}$	72.90%	0.0	1.0	0.0	0.0
DP5	$a/(f \times T_p) = \text{constant}$	72.90%	0.0	0.0	-1.0	0.0
DP6	$(a^{5.5} \times v \times \xi)/T_p = \text{constant}$	77.50%	0.0	6.5	-1.0	1.0
DP7	$(a \times T_p \times v)/f = \text{constant}$	74.20%	0.0	1.0	0.0	0.0
DP8	$a^{5.5} \times T_p \times \xi = \text{constant}$	82.60%	0.0	5.5	1.0	1.0
DP9	$a \times T_p \times v = \text{constant}$	74.10%	0.0	2.0	0.0	0.0
DP10	$(a^2 \times T_p \times \xi)/v = \text{constant}$	74.40%	0.0	1.0	2.0	1.0
DP11	$(a^2 \times \xi)/v = \text{constant}$	76.00%	0.0	1.0	1.0	1.0
DP12	$a^{5.5} \times f \times \xi = \text{constant}$	76.80%	0.0	6.5	0.0	1.0



Observations

- A user-defined basic dimension (Cost) has been introduced
- Redundant design principles can be seen (For example DP2, DP3 and DP4)
- DP1 is a false design principle, arising due to difference in magnitudes of D and t

